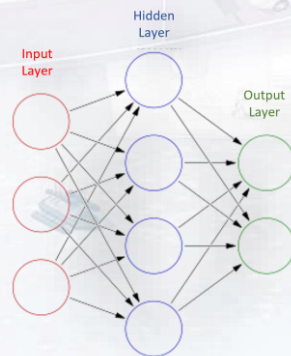


From Run-to-Failure to Run-to-Insight

AI-Driven Early Failure Detection in Powertrain & e-Axle R&D



	Traditional Testing (Run-to-Failure)	MIG16 EFD (Run-to-Insight)
Test Conclusion	Catastrophic Breakdown	Controlled Shutdown at targeted damage level.
Prototype Status	Completely Destroyed	Preserved. Housings, shafts, and adjacent gears are saved and reusable.
Data Quality	Post-Mortem Guesswork	High-resolution damage propagation tracking captured in real-time.
Cost Impact	Total Loss of Specimen	Intensive, multi-cycle testing using a single prototype investment.

The MIG 16 Early Failure Detection (EFD) System

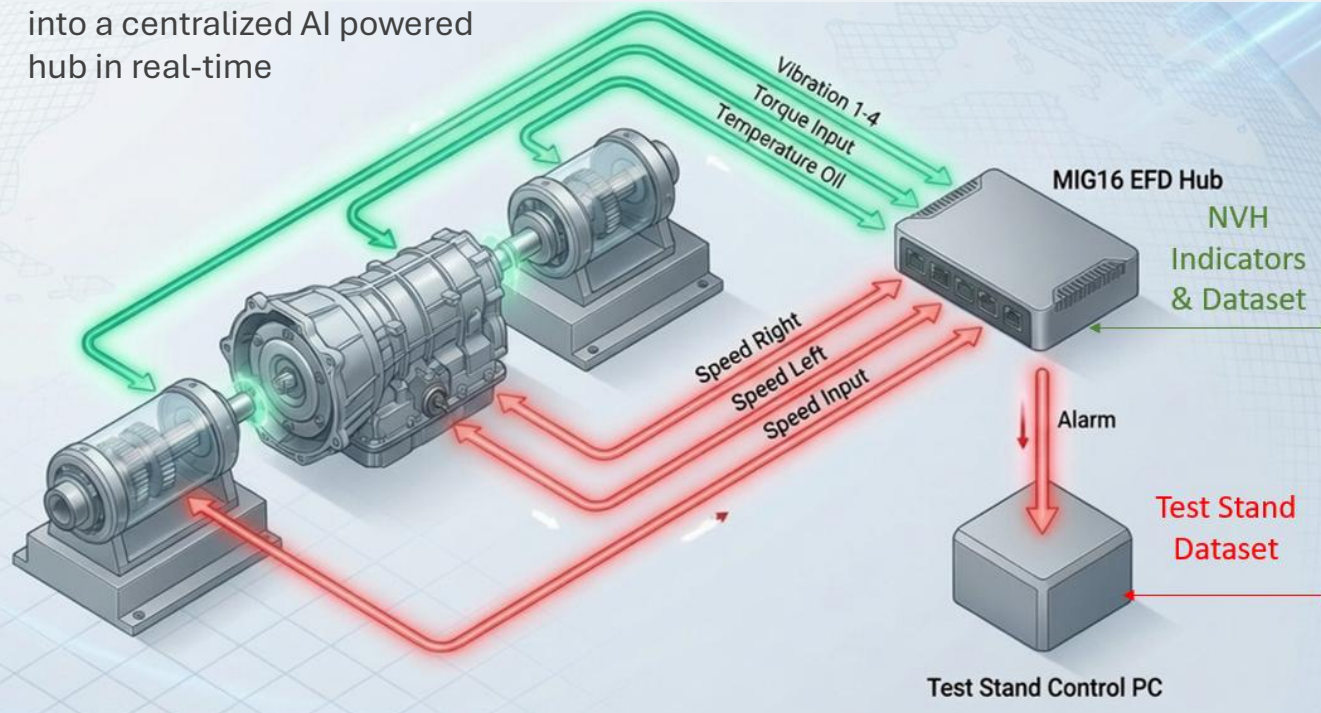


24-bit multi-channel
data acquisition.

100 KHz digitization for
ultra-precise NVH analysis.

Real-time AI-NVH classification
without segmentation constraints.

The EFD system routes complex mechanical inputs into a centralized AI powered hub in real-time

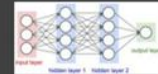


Big Data Solution
On/off Premise Cloud
Data Lake



AQS Server and
tools

Machine Learning,
AI platforms



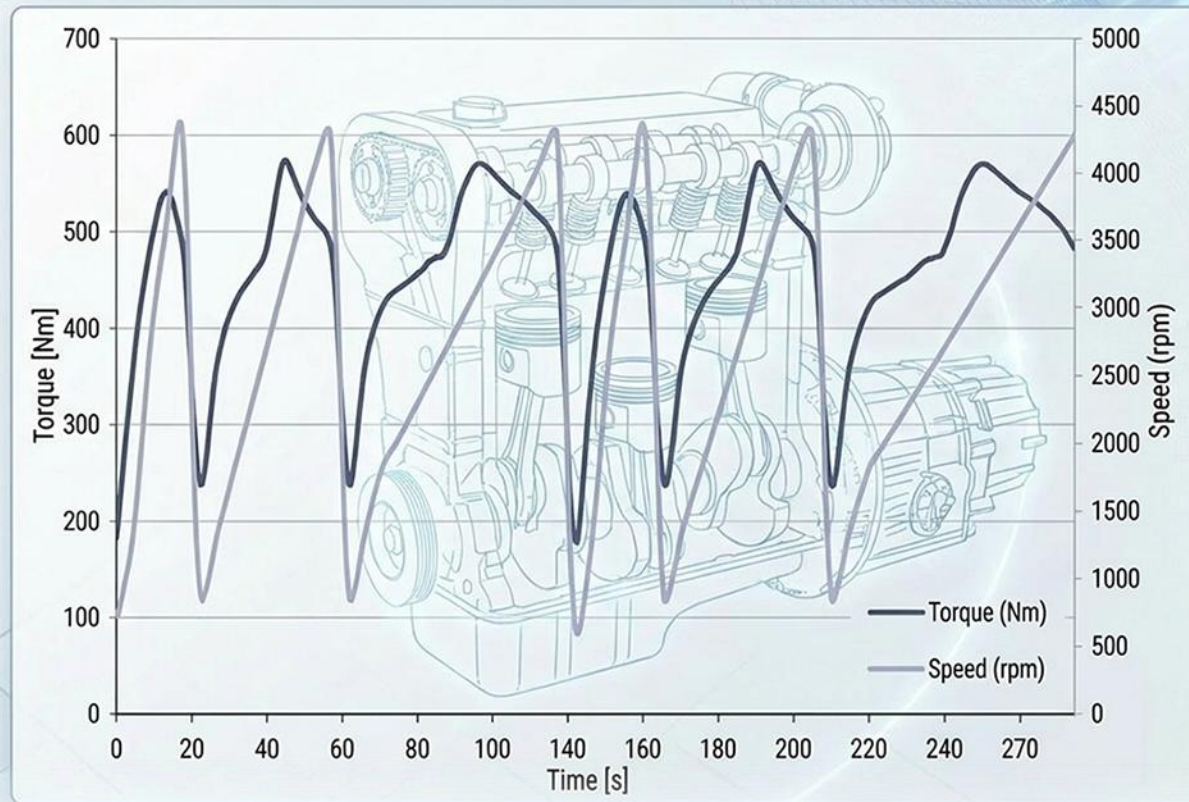
Data Scientist
access frameworks



Customer specific
solution and DBs

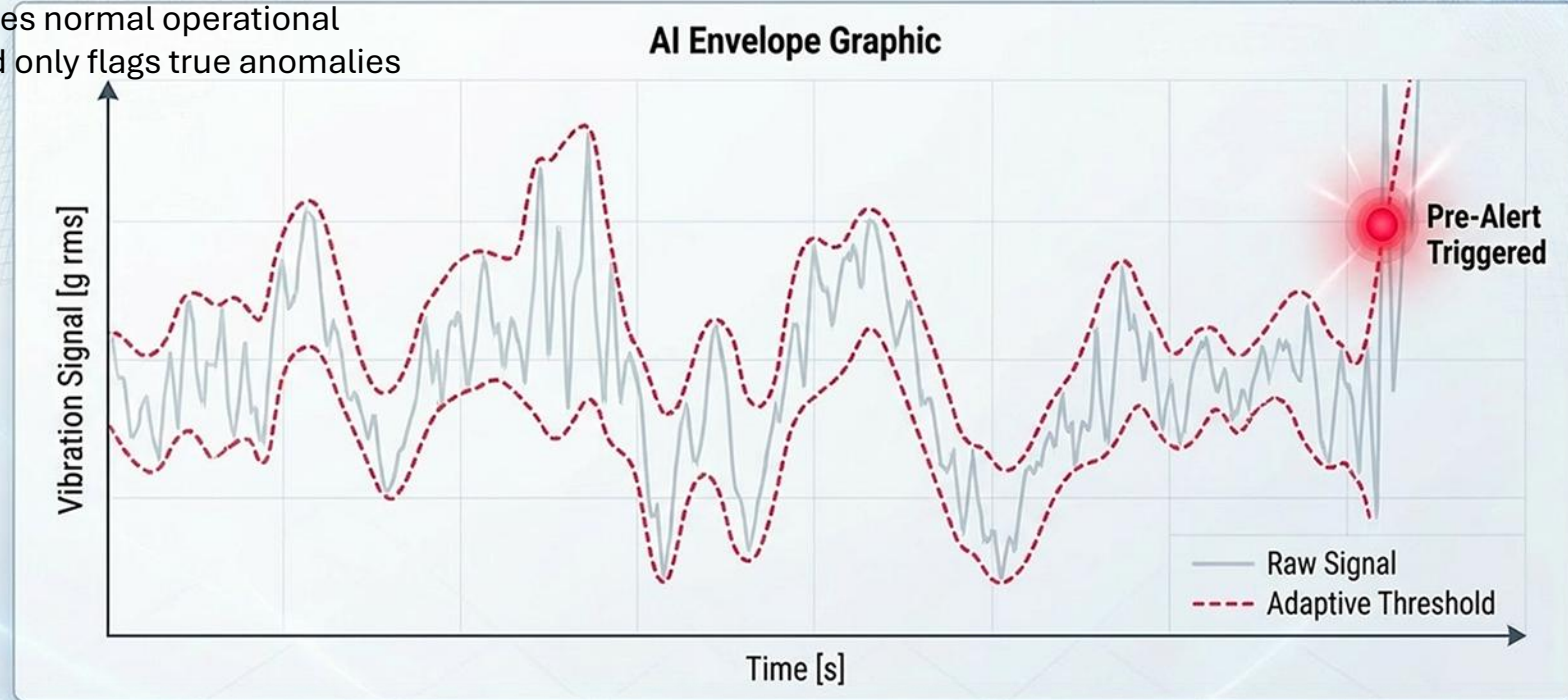


Engine testing requires navigating complex transmission interactions and aggressive acceleration phases. The MIG16 tracks limits dynamically across these intense load profiles, safely monitoring engines, transmissions, and hybrid turbochargers without missing a micro-failure.



Adaptive Limits, Not Static Thresholds

The AI learns conformity based on specific operating points (torque, speed, temperature) automatically. It recognizes normal operational spikes and only flags true anomalies



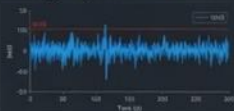
The EFD
system
calculates
real time NVH
Indicators in
three
distinctive
domains



Time Domain

Method: Digital band-pass filters and Root Mean Square (RMS) algorithms over 100ms timebases.

Diagnostic Target: General vibration energy tracking; ideal for spotting slow-growing, systemic friction.



Frequency Domain

Method: High-resolution Spectrums (down to 0.1 Hz resolution and up to a maximum frequency of 100 kHz) using digital integration and FFT-Filters.

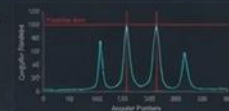
Diagnostic Target: Extracting specific, characteristic damage types hidden beneath engine noise.



Angular Domain

Method: Vibration signals are digitally resampled to a 360-sample-per-rotation (1° resolution) angular domain.

Diagnostic Target: Pinpointing irregular combustion events precisely mapped to the crankshaft's physical position.



Indicator Name	RMS (Root Mean Square)	SF (Speed Fluctuation)	OS (Order Spectrum)
Core Mechanism	Computes the short-time effective value of raw vibration signals.	Applies a band-pass filter (30-300 Hz) to isolate deviations in mean speed.	Resamples time-based data into angular-synchronous data via Fourier transform.
Integration/Reaction	100ms (Very Fast)	100ms (Very Fast)	Continuous Tracking
Primary Target Defect	Overall noise indicator; catches sudden, catastrophic defects .	Shaft health; isolates torsional vibrations and partial shaft fractures .	Pinpoints specific mechanical noise sources (gears, individual bearings).

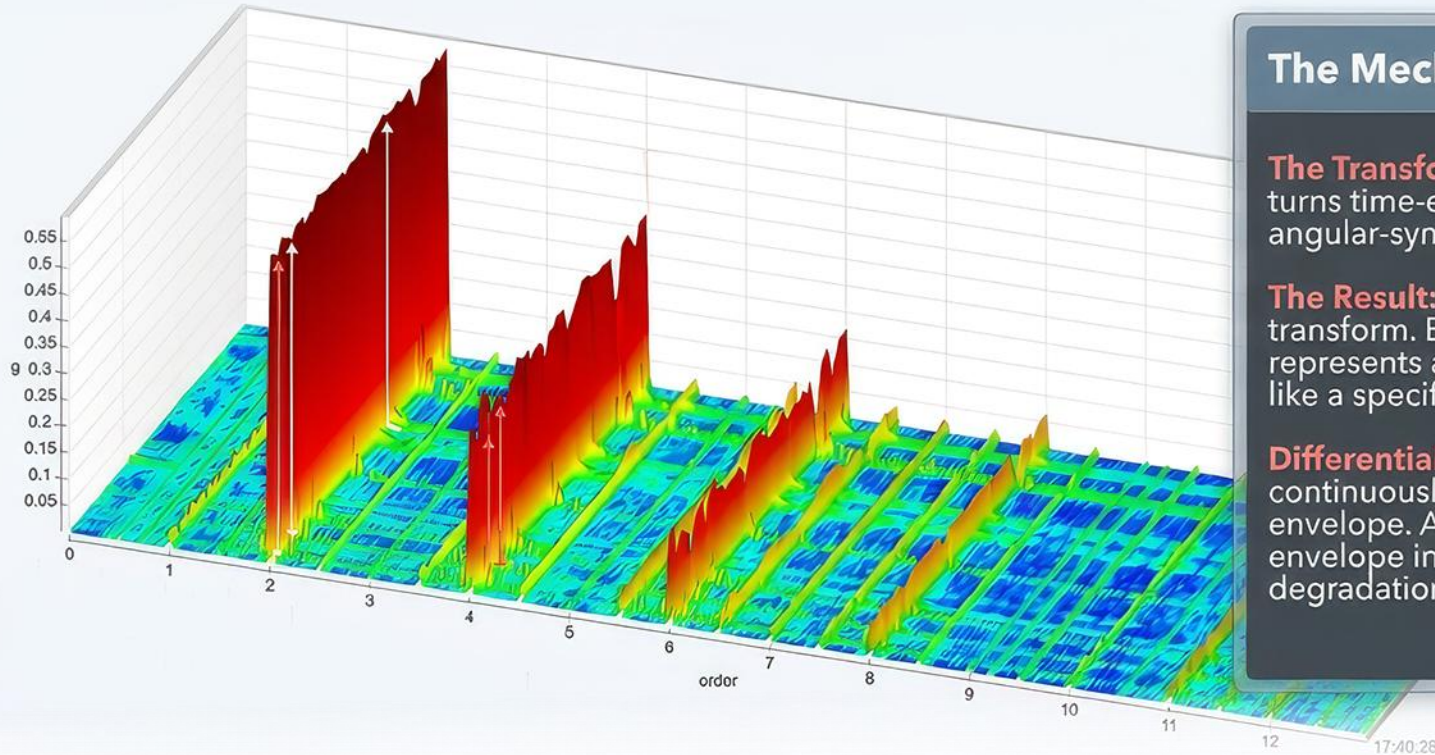
$$s_{\text{eff}} \approx \sqrt{\frac{1}{T} \sum_{i=1}^n x_i^2 \Delta t_i}$$
$$= \sqrt{\frac{1}{T} [x_1^2 \Delta t_1 + x_2^2 \Delta t_2 + x_3^2 \Delta t_3 + \dots + x_n^2 \Delta t_n]}$$

- Acts as the primary overall health guard dog.
- Continuously calculates effective value over a 100ms integration time.
- Guarantees an immediate reaction to sudden mechanical anomalies.





- While overall vibration captures loud, obvious damage, **SF** looks for subtle hesitations in the shaft's rotation.
- By applying a strict band-pass filter, the system calculates the **effective deviation** of the mean speed.
- **Primary Application:** Instantly flags partial shaft fractures **before** complete structural failure occurs.



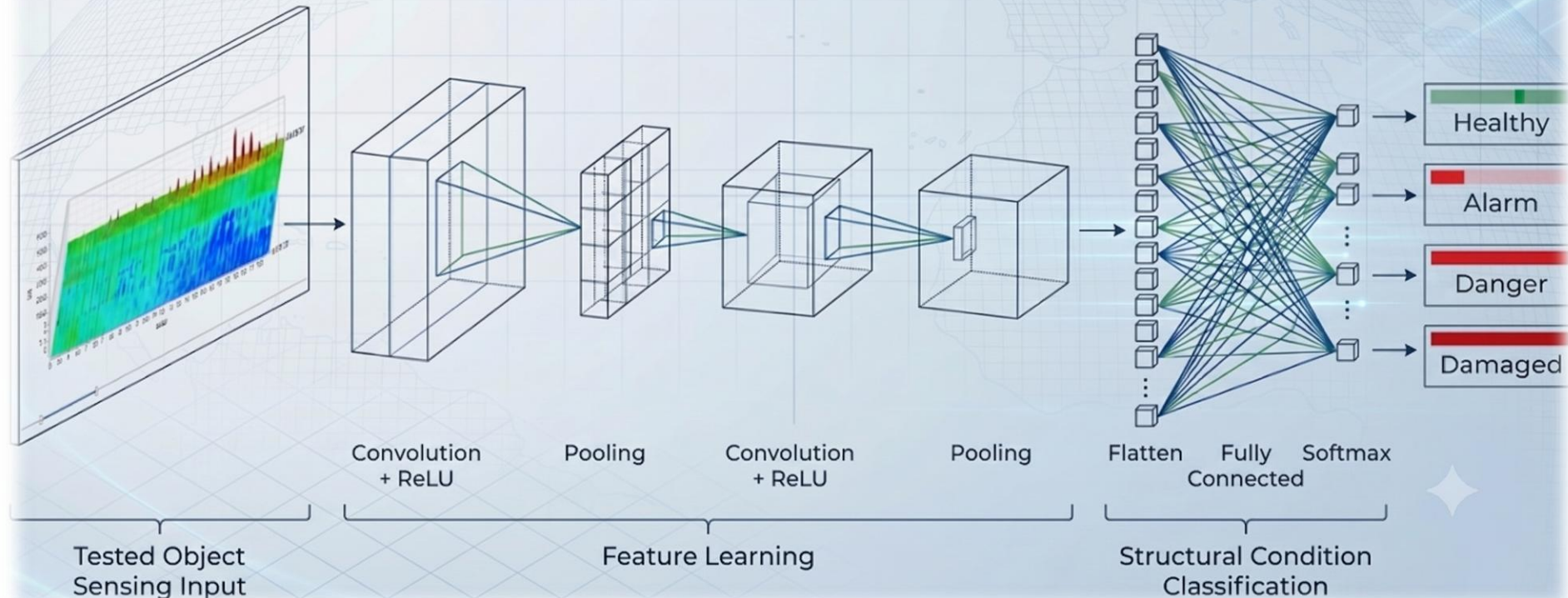
The Mechanics of OS

The Transformation: Digital resampling turns time-equidistant signals into angular-synchronous signals.

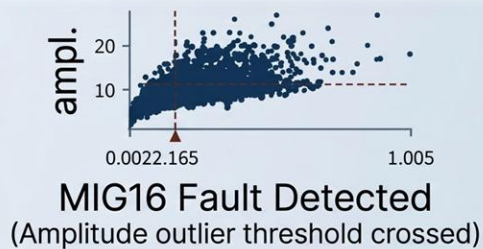
The Result: A high-resolution Fourier transform. Every 'order' (peak) represents a distinct mechanical source like a specific gear or bearing.

Differential Tracking: The system continuously builds an operational envelope. Any deviation from this envelope instantly flags component degradation.

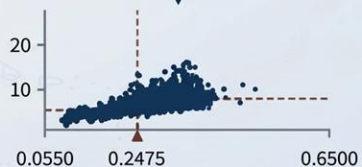
Transforming raw acoustic data into classified structural states via Convolutional Neural Networks.



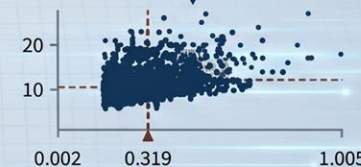
Definitive Root Cause Isolation.
The AI does not just detect failure;
it classifies the origin. By evaluating
multi-sensor vibration scatter-plots,
the system pinpoints specific
microscopic defects—from gear tooth
pitting to bearing damage.



< | >



Electrical Anomaly



Mechanical Anomaly



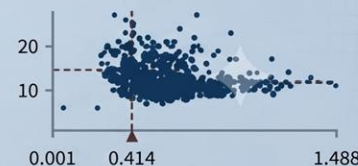
Inverter



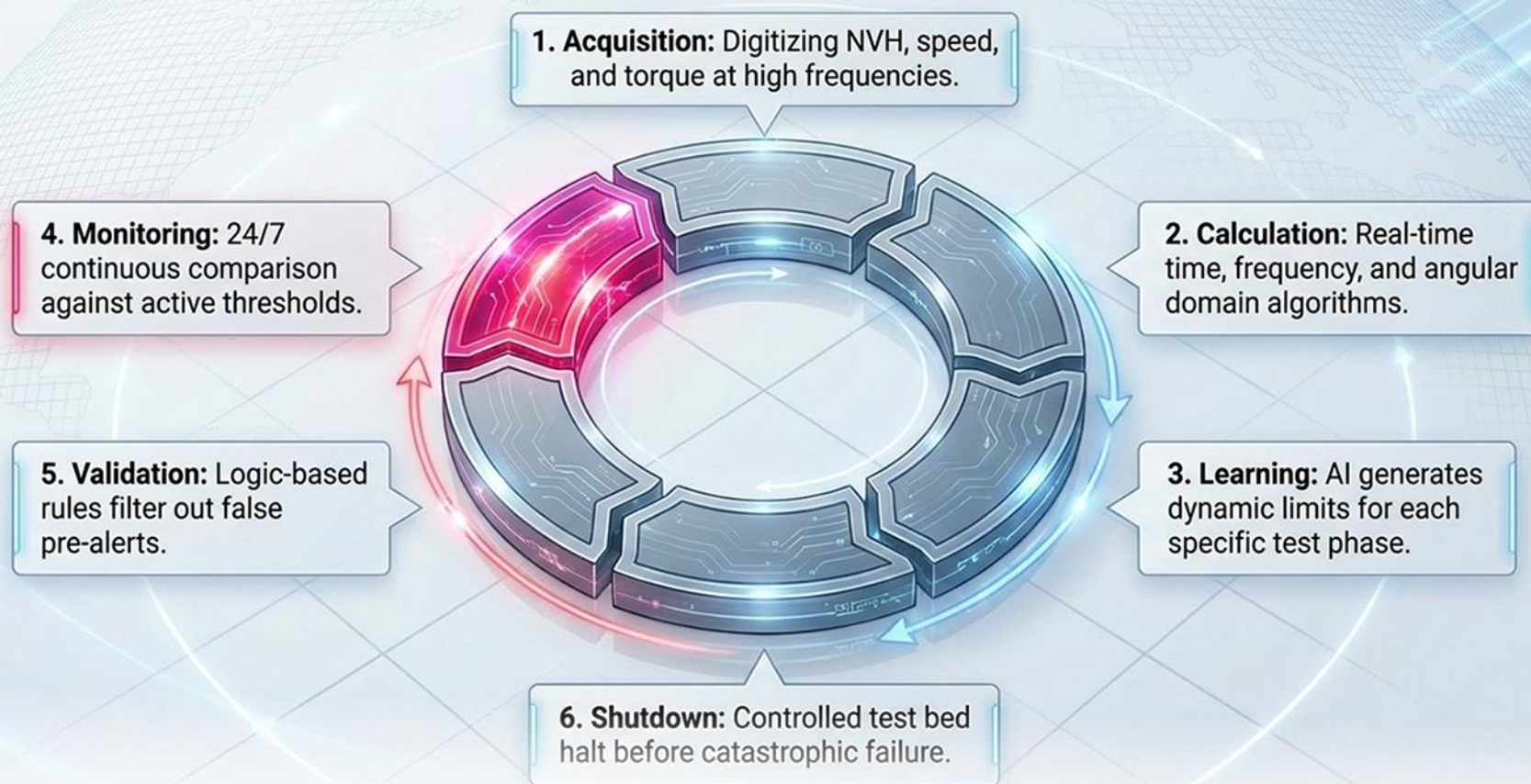
Motor

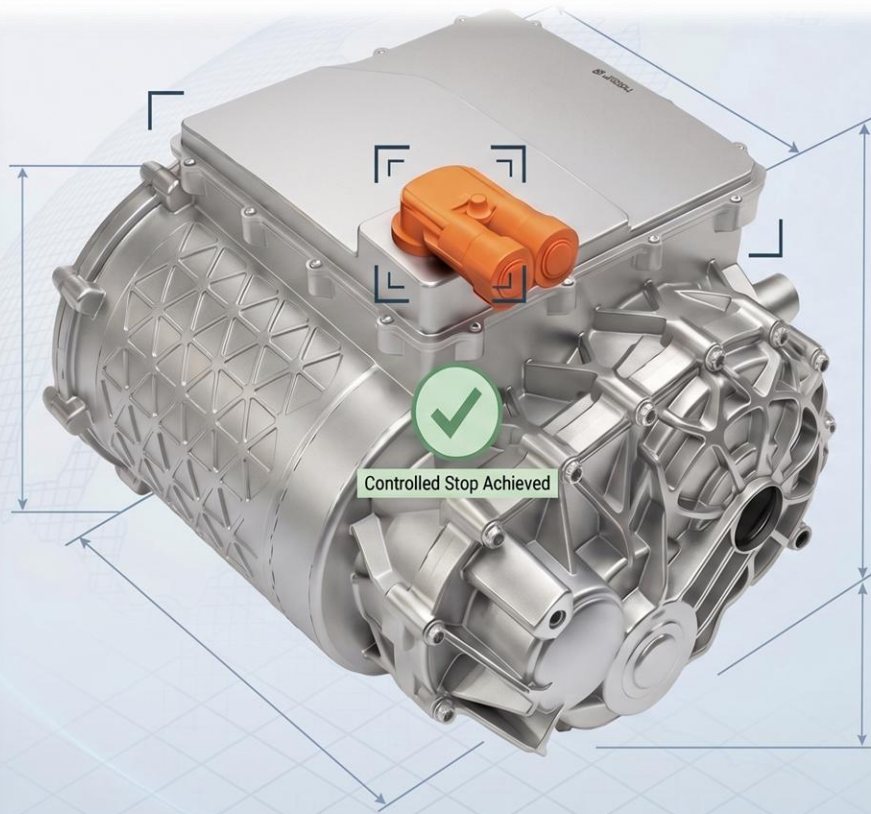


Gear

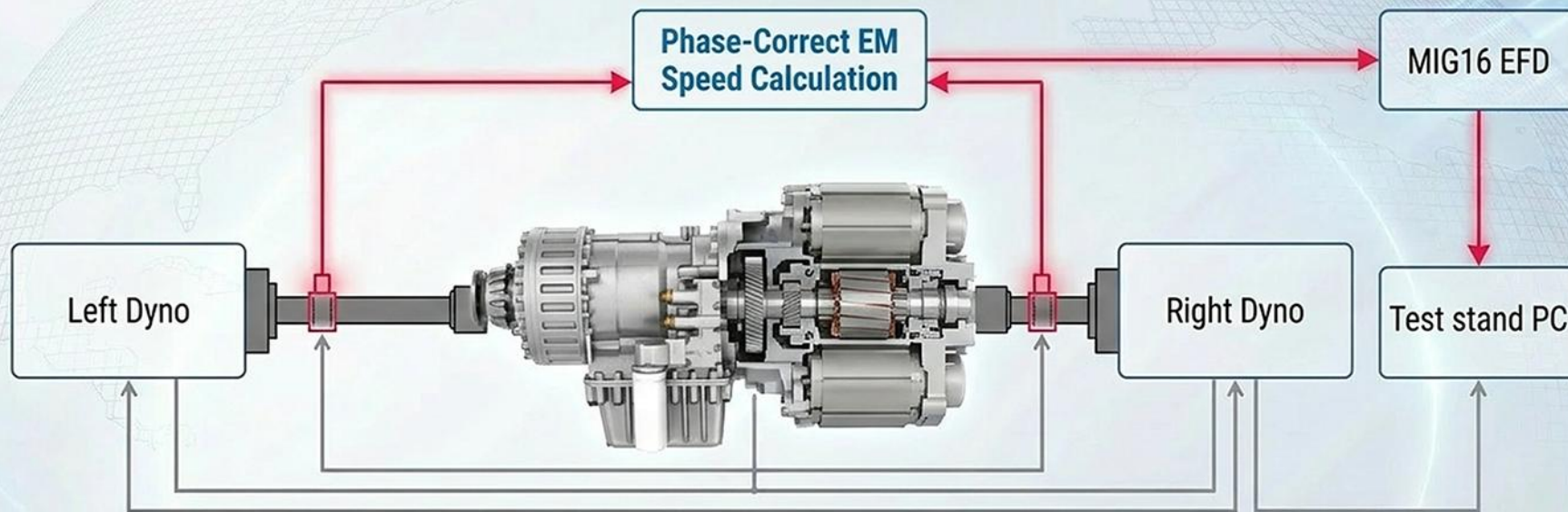


Bearing



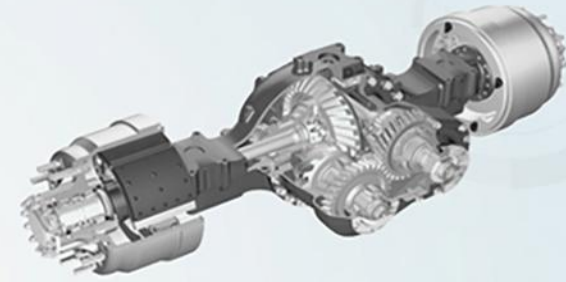
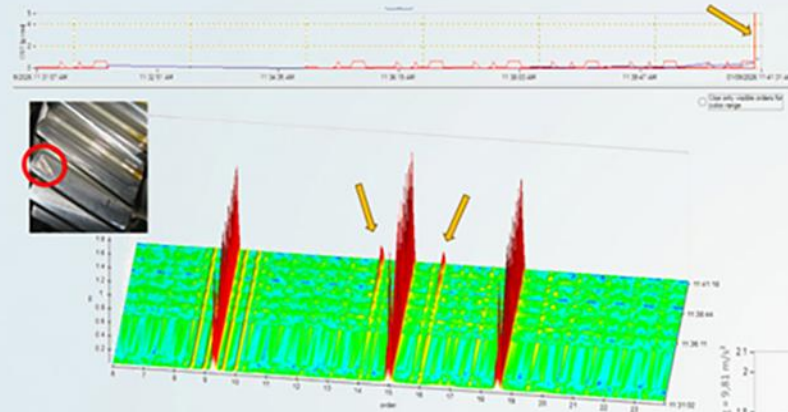


- > Micro-second shutdown commands protect expensive test specimens from collateral destruction.
- > Housings, shafts, and adjacent gears are saved and reusable for intensive analysis.
- > Enables automated test tracks with up to 10 vehicles running simultaneously without cascading failure risks.
- 📈 Subjective human NVH sensitivity is replaced by deterministic, objective digital signatures.

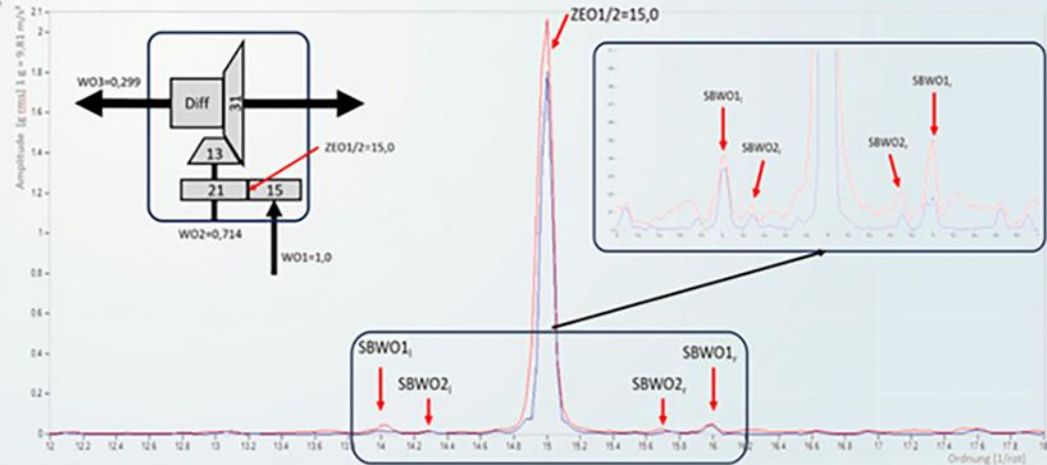


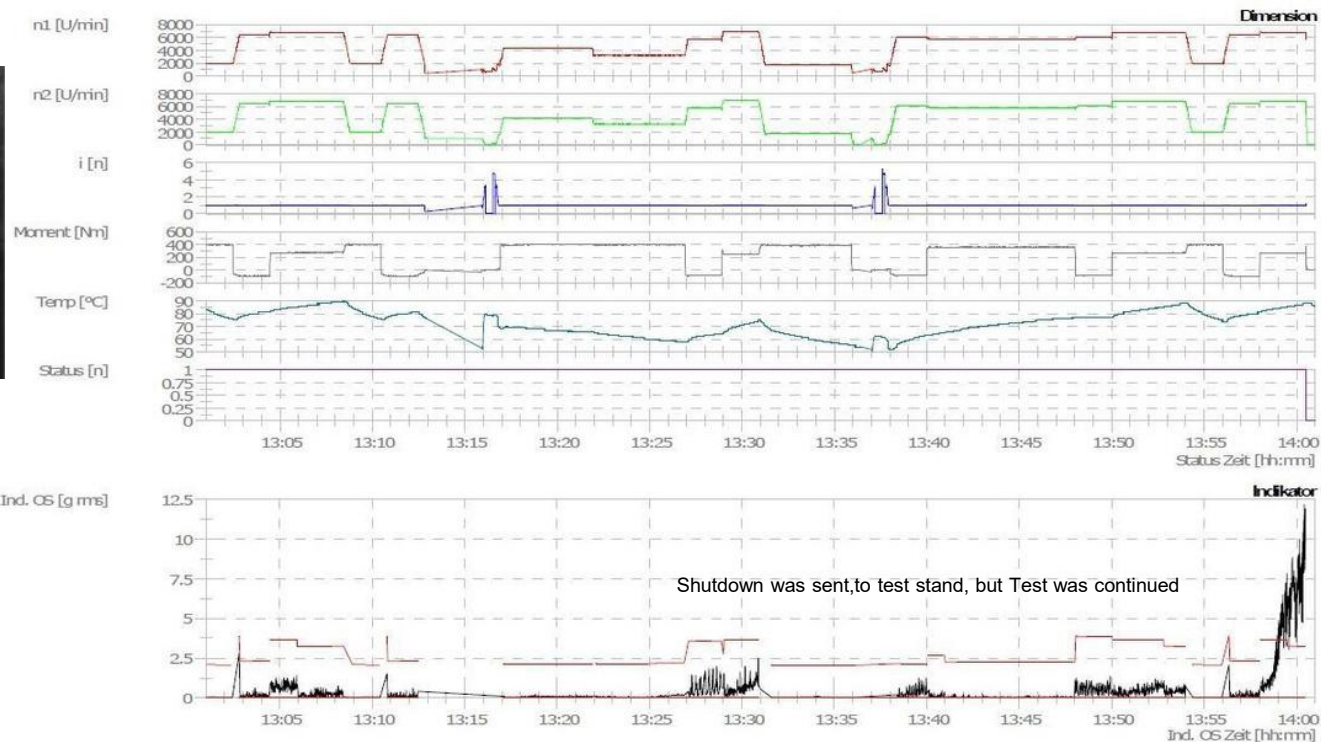
In an E-Axle testing setup, the MIG16 calculates differential speed and average speed to generate an exact, phase-correct EM speed. This cuts through high electrical noise environments to detect microscopic gear pitting or inverter housing vibrations in real-time, protecting multi-million dollar e-axle prototypes.

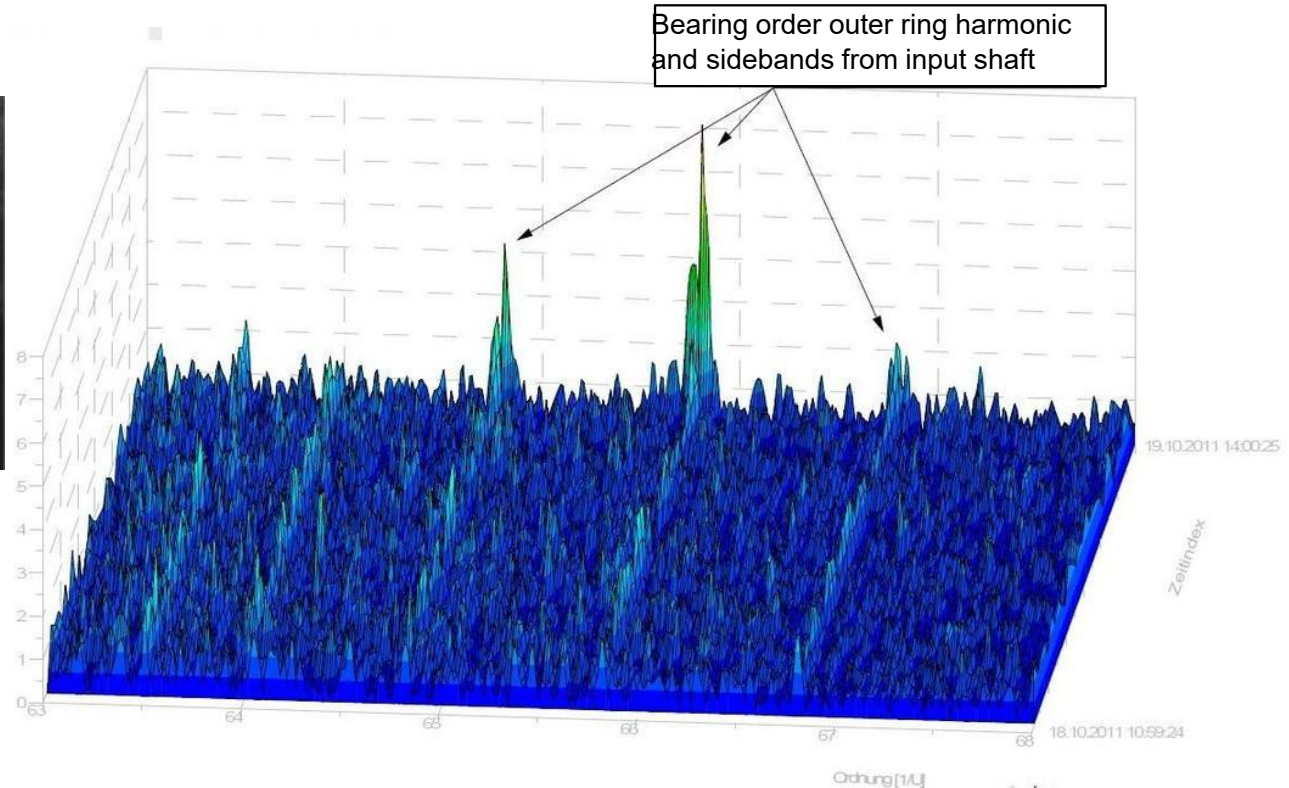
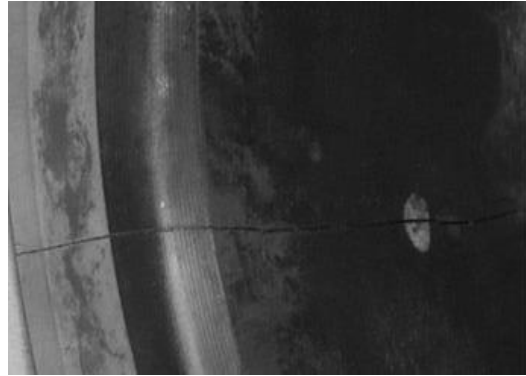
Shutdown Diagnosis in relation to Sideband Growth

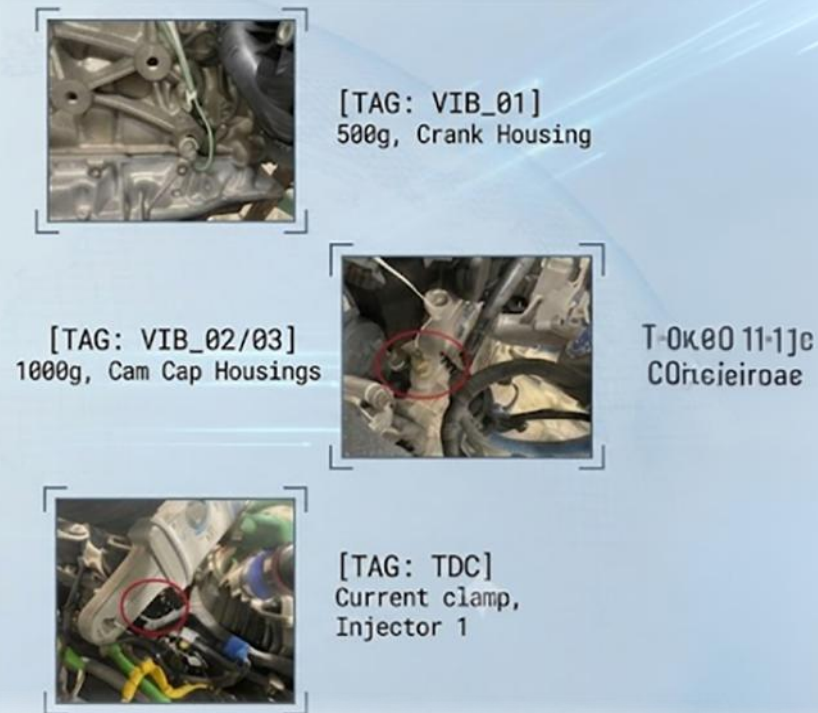


ZEO: Tooth mesh order
 WO: Shaft order
 SBWO: Side band shaft order

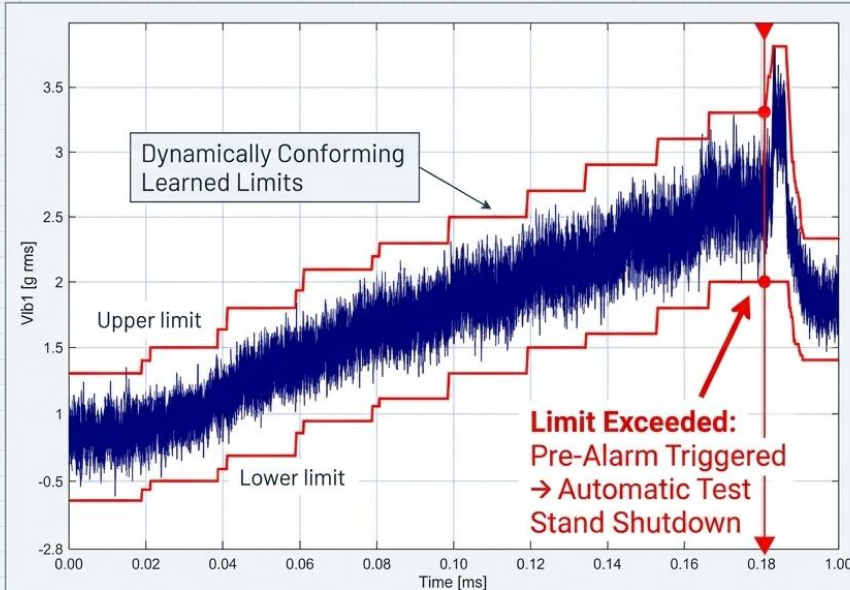








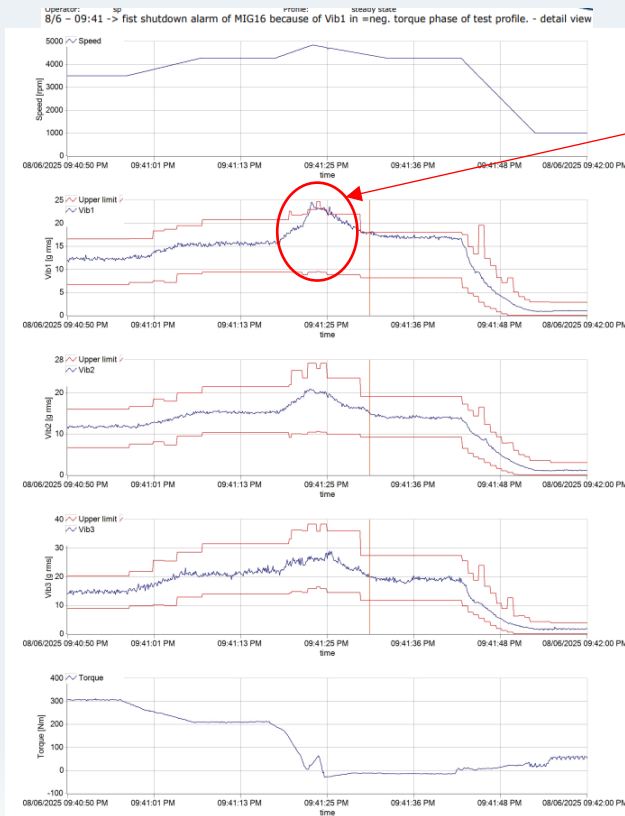
The Envelope of Safety Concept



Real World Impact



DIAGNOSTIC EVENT 20250807:
Bearing failure allowed piston
to travel beyond tolerance,
slapping the cylinder head.
Caught via envelope breach.

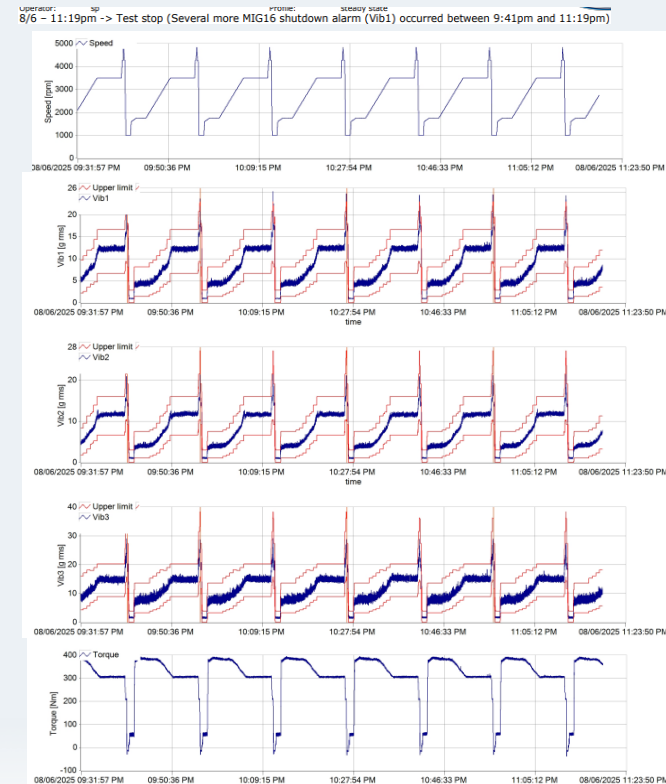


8/6 - 09:41pm -> first shutdown alarm of MIG16 because of Vib1 in neg. torque phase of test profile. A clear trend increase of Vib1 over the previous test hours can be seen.

This increasing trend is particularly evident on Vib1. An analysis of the raw data shows that no combustion event or similar is responsible for this increase. Rather, it is a general increase in overall noise. This trend increase is typical of a wear damage. The fact that the trend is only visible on Vib1 is consistent with the assumption of a clutch failure.

All Vib sensors do not show any increasing trend in pos. torque load steps.

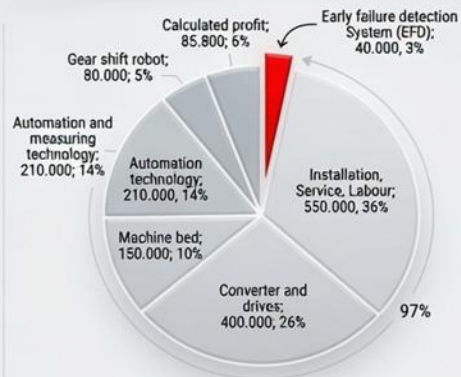
8/6 - 11:19pm -> Test stop (Several more MIG16 shutdown alarm (Vib1) occurred between 9:41pm and 11:19pm)





Test Bed Utilization: 65% → 90%

Eliminates catastrophic downtime and allows precise test-stop targeting.



Capital Efficiency

The EFD system represents only 3% of total expenditure, yet protects 100% of the capital investment.

**ROI
< 12
Months**

Pays for itself within one year through prototype preservation alone.

Agility

Setup to Monitoring in Minutes

Standard screwed/glued sensors and CAN-bus integration allowed the Instrumentation team to prep the TDC trigger in under 10 minutes.

Precision

Beyond Catastrophic Failure

MIG16 EFD detects microscopic wear and irregular combustions via high resolution order tracking and 1° angular resolution. Don't wait for parts to break.

Proven Integration

A Decade of Trust

The Transmission Lab in Livonia has successfully relied on the MIG16 EFD system for over 10 years.

Leverage red-ant onsite training today to integrate Early Failure Detection into all standard durability testing workflows.

Headquarter Munich, Germany

- Tokyo & Nagoya, Japan, TOYO Corp.
- **Fremont CA & Detroit MI , USA, TOYOTech**



- Shenzhen, China
- Suwon, Korea
- Sao Paulo, Brazil
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				 HONDA	 TOYOTA
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red-ant operates 11 offices worldwide, supporting over 200 industrial customers and delivering more than 700 systems.



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